

Q. what's the relation between  $\underline{D^b(A)}$  and  $D^b(A^\#)$ ?

If  $A^\#$  is obtained by tilting at a t-structure  $(\tau, \mathcal{F})$  in  $A$  and  $(\mathcal{K}, \mathcal{F})$  is co-tilting which means  $\forall E \in A, \exists F \in \mathcal{F}$  and an  $F \rightarrow E$ , then  $D^b(A) \cong D^b(A^\#)$ .

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Slicing on  $\mathcal{D} : \{P(\emptyset)\}_{\emptyset \in \mathbb{R}}$

$$(1) P(\emptyset+1) = P(\emptyset)[1]$$

$$(2) \text{Hom}(P(\emptyset_1), P(\emptyset_2)) = 0 \quad \emptyset_1 > \emptyset_2$$

(3)  $E \in \mathcal{D}$ , then exists a HN filtration.

we view objects in  $P(\emptyset)$  as objects of plane  $\emptyset$ .

EX. 6 the plane  $\emptyset_i$  in the HN filtration of any object  $E \in \mathcal{D}$  is unique.

$$\emptyset_P^+(E) := \emptyset_1, \quad \emptyset_P^-(E) := \emptyset_n$$

Let  $\mathcal{A} = \mathcal{P}(0, 1] =$  full extension-closed subcategory generated by all  $\mathcal{P}(\emptyset)$  for  $\emptyset \in (0, 1]$

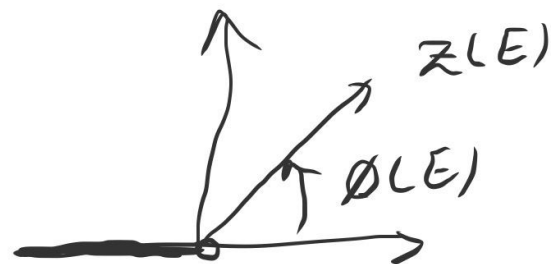
$$= \{ E \in \mathcal{D} : \emptyset_p^+(E) \leq 1 \text{ and } \emptyset_p^-(E) \geq 0 \}.$$

Then  $\mathcal{A}$  is the heart of a bounded  $t$ -structure on  $\mathcal{D}$ .

Def. A Bridgeland stability condition on a triangulated category  $\mathcal{D}$  is a pair  $(Z, \mathcal{P})$  where  $Z: K(\mathcal{D}) \rightarrow \mathbb{C}$  group homomorphism (called central charge) and  $\mathcal{P}$  is a slicing. So that for every  $\emptyset \neq E \in \mathcal{P}(\emptyset)$  we have

$$Z(E) = m(E) \exp(i\pi\emptyset) \text{ for some } m(E) \in \mathbb{R}_{>0}.$$

Def. A stability function on an abelian category  $\mathcal{A}$  is a group homomorphism  $Z_{\mathcal{A}}: K(\mathcal{A}) \rightarrow \mathbb{C}$  st  $\neq 0 \in \mathcal{A}$ ,  
 $Z_{\mathcal{A}}(E) \in \text{IH} := \{ m \exp(i\pi\phi) : m \geq 0, 0 < \phi \leq 1 \} \subseteq \mathbb{C}$



We say  $\neq 0 \in \mathcal{A}$  is (semi)stable w.r.t  $Z_{\mathcal{A}}$  if  $\forall \neq 0 \in F \subset E$   
in  $\mathcal{A}$ ,  $\phi(F) \leq (\leq) \phi(E)$

Def. A Harder-Narasimhan filtration of  $\neq 0 \in \mathcal{A}$  is a finite filtration

$$0 = E_0 \subset E_1 \subset \dots \subset E_n = E$$

such that  $E_i/E_{i-1}$  are semistable w.r.t  $Z_{\mathcal{A}}$  with

$$\phi(E_1/E_0) > \phi(E_2/E_1) > \dots$$

Prop. To give a Bridgeland stability condition  $(Z, P)$  on  $D$  is equivalent to give a pair  $(A, Z_A)$  where  $A$  is the heart of a bounded t-structure on  $D$  and  $Z_A$  is a stability function which satisfies HN property.

Pf.  $(Z, P) \rightsquigarrow (A, Z_A)$ .

$$A := P(0, 1] \text{ heart} \quad \Rightarrow \quad K(D) = K(A)$$

$$\text{so the central charge defines } Z_A := Z : K(A) \rightarrow \mathbb{C}.$$

$$\forall E \in A, \quad 0 < \phi(Z(E)) \leq 1 \quad \rightsquigarrow \quad Z_A(E) \in \mathbb{H}$$

$$(A, Z_A) \rightsquigarrow (Z, P)$$

$$\text{for } \phi \in (0, 1] \quad P(\phi) = \{ \underset{\phi}{Z_A\text{-semistable objects in } A \text{ of phase } \phi} \}.$$

$$P(\phi + n) = P(\phi)[n] \quad n \in \mathbb{Z}.$$

• Hom vanishing : definition of heart +  $E, F \in A$  which are  $\mathbb{Z}_A$ -stable  
 $\emptyset(E) > \emptyset(F)$

• Filtration :  $(E \in D \quad \exists \text{ filtration by } \text{Hom}(E, F) \in \mathbb{Q}$   
 cohomology objects  $A_i \in A[k_i]$ )

$$0 \rightarrow A_{i,1} \rightarrow A_{i,2} \hookrightarrow \dots \hookrightarrow A_{i,m_i} = A_i$$

which is HN filtration of  $A_i$  w.r.t  $\mathbb{Z}_A$

$\mathbb{Z} := \mathbb{Z}_A : K(P) \rightarrow \mathbb{R}$  and by our construction  $\mathbb{Z}$   
 $K(A)$  is compatible with  $P$ . □

$\Rightarrow$  stable objects are the same w.r.t these two notions.

Example.  $C$ : smooth projective curve /  $\mathbb{C} \rightsquigarrow A = \text{Coh}(C)$

$$\mathbb{Z}_A(E) = -\deg(E) + i \, \text{rk}(E)$$

$\rightsquigarrow (A, \mathbb{Z}_A)$  is a stability condition on  $D^b(C)$

Semistable objects in  $D^n(C)$  : shift of  $\mu$ -semistable vector bundles on  $C$ , or zero-dimensional torsion sheaves.

Ex. 7  $S$ : smooth projective surface, then there is no stability function  $Z$  which sends objects of  $A = \text{coh}(S)$  to  $\text{lt}$ .

Space of stability conditions.

We need to restrict to  $\mathcal{S} = (Z, P)$  satisfying two extreme assumptions:

(1)  $\Lambda$ : finite dim. lattice with a map  $\lambda: K(P) \rightarrow \Lambda$

$$\begin{array}{ccc} \text{s.t.} & Z: K(D) & \longrightarrow \mathbb{C} \\ & \searrow \lambda & \nearrow Z\lambda \\ & \Lambda & \end{array}$$

usually  $\Lambda = K_{\text{num}}(D)$ :  
quotient of  $K(D)$  by the  
null space of Euler form  
 $\chi(E, F) = \sum_i \dim H^i(E, F)$

(2) Let  $\|\cdot\|$  arbitrary fixed norm on  $\mathcal{A}_{\mathbb{R}} = \mathcal{A} \otimes \mathbb{R}$ ; we assume  $\sigma$  satisfies the "support property",

$$\inf \left\{ \frac{|\mathcal{Z}(E)|}{\|E\|} \mid E \in \sigma\text{-stable} \right\} > 0$$

$\leadsto \text{Stab}_{\Lambda}(D)$ , the set of stability conditions on  $D$  satisfying the above two conditions.

generalised metric on the set of slices

$$\left\{ \begin{array}{l} \mathcal{G}_1 = (\mathcal{Z}_1, P_1) \\ \mathcal{G}_2 = (\mathcal{Z}_2, P_2) \end{array} \right. \quad d_{\text{slice}}(P_1, P_2) = \sup_{e \neq E \in D} \left\{ \begin{array}{l} |\phi_{P_2}^+(E) - \phi_{P_1}^+(E)|, \\ |\phi_{P_2}^-(E) - \phi_{P_1}^-(E)| \end{array} \right\}$$

combined this metric with metric  $\in [0, +\infty]$ .

on  $\tilde{\Lambda} := \text{Hom}(\Lambda, \mathbb{C})$  induced by  $\|\cdot\|$

we get a generalised metric on  $\text{Stab}_{\Lambda}(D)$ :

$$d(\mathcal{G}_1, \mathcal{G}_2) = \sup \left\{ d_{\text{slice}}(P_1, P_2), \|\mathcal{Z}_1 - \mathcal{Z}_2\| \right\}.$$

Thm. The space  $\text{Stab}_n(\mathbb{D})$  of stability condition is a smooth finite-dimensional complex manifold s.t

$$\mathcal{Z} : \text{Stab}_n(\mathbb{D}) \rightarrow \text{Hom}(n, \mathbb{C})$$

$$\sigma = (\mathcal{Z}, P) \mapsto \mathbb{Z}$$

i, a local homeomorphism at every point of  $\text{Stab}_n(\mathbb{D})$ .

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$$GL^+(2, \mathbb{R}) \rightsquigarrow \widetilde{GL}^+(2, \mathbb{R}) = \{ (T, f) \mid T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ orientation preserving linear isomorphism} \}$$

$$f: \mathbb{R} \rightarrow \mathbb{R} \text{ increasing map}$$

$$f(\theta+1) = f(\theta) + 1$$

such that the inclusion map

$$\frac{\mathbb{R}^2 \setminus \{0\}}{\mathbb{R}_{>0}} \cong S^1 = \mathbb{R} / 2\pi \mathbb{Z} \text{ are the same}$$

e.g. id can be lifted to  $(\text{id}, f, \theta \mapsto \theta + 2\pi k) \in \widetilde{GL}^+(2, \mathbb{R})$ .

$$k \in \mathbb{Z}$$



$$\text{Stab}_\Lambda(D) \times \widetilde{\text{GL}}^+(2, \mathbb{R}) \longrightarrow \text{Stab}_\Lambda(P)$$

$$(G = (Z, P), (T, f)) \longmapsto G' = (Z', P')$$

$$Z' = T^{-1} \circ Z, \quad P'(\emptyset) = P(f(\emptyset))$$

\* Existence of objects w.r.t stability condition  $G$  and  $G'$  are the same.  
 but only the phase have been related.

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Stability condition on curves of  $g > 0$

$\Lambda := K_{\text{num}}(D^b(C))$  we call the numerical stability condition.  
 Smaller pyramid curve of  $g > 0$

thm.  $\text{Stab}_\Lambda(D^b(C))$  consists of exactly one  $\widetilde{\text{GL}}(2, \mathbb{R})$ -orbit  
 i.e.  $\text{Stab}_\Lambda(C) / \widetilde{\text{GL}}^+(2, \mathbb{R}) = \{pt\}$ .